

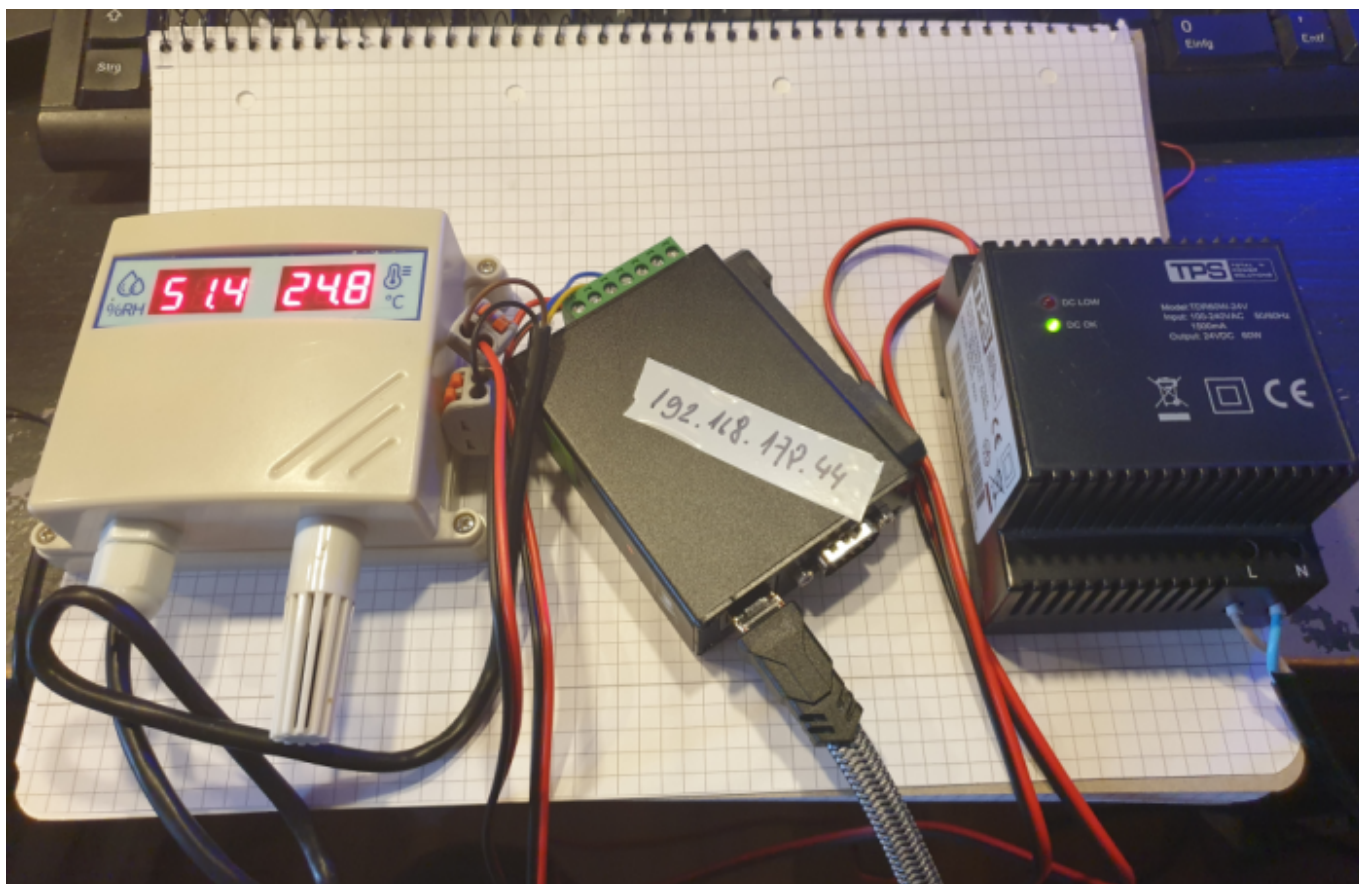
lamaPLC: S7-1500 and UICPAL Temp.humi.sensor Modbus TCP communication

UICPAL's temperature/humidity measuring unit is a fairly cost-effective solution for controlling the air in closed spaces. The unit is also available on Aliexpress, for example, at a price well below 100 euros. The advantage is that it displays the measured values and has a [Modbus](#) communication solution. This function can be well integrated with industrial equipment, for example it can be used together with S7 PLC, the solution below describes this possibility.

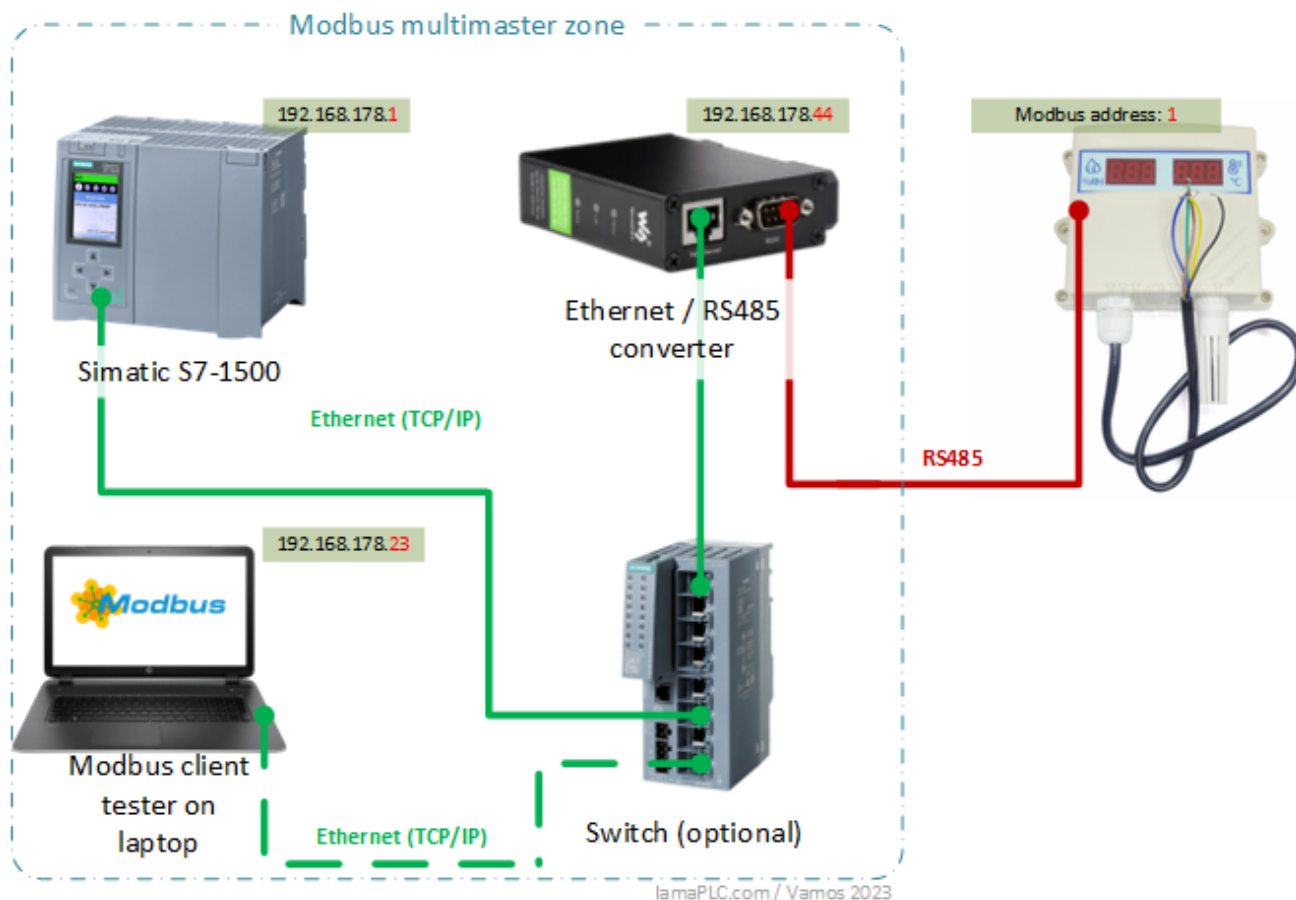


A more detailed description of the UICPAL temperature / humidity meter [can be found here](#).

Unfortunately, the unit (as far as I know) does not have a "CE" certification, which can make its application difficult in some cases.



The UICPAL unit and the S7-1500



The UICPAL unit has RTU communication, which should be connected with an ethernet/RS485 converter as a cost-effective solution. This converter is now available directly from Simatic. It is worth starting the testing with a Modbus client tester program. If UICPAL is available from here, then there will be no major problem with Simatic.

The steps for setting up communication:

1. Switching on UICPAL, wiring with the ethernet/RS485 converter (A TX+, B RX-). The converter is [described here](#). UICPAL is [described here](#).
2. Connecting the laptop to the ethernet/RS485 converter
3. ethernet/RS485 converter settings:
4. Setting the IP address (in the example: 192.168.178.44)
5. Setting the RS485 communication parameters: 8n1, speed: 9600 baud, addr: 1
6. Testing communication from the laptop. If the unit is not available, review the parameters and possibly replace the Modbus wires
7. If the Modbus communication works from the laptop; disconnect.
8. Uploading the PLC program, testing the PLC communication.

The S7 programm for communication

```

1  #ston(IN:=NOT(#stonb),
2    PT:=t#2s);
3
4  #stonb := #ston.Q;
5
6  IF #stonb THEN
7    IF #start THEN
8      #start := FALSE;
9    ELSE
10     #start := TRUE;
11    END_IF;
12    "mbRead".liveBeat := "mbRead".liveBeat + 1;
13  END_IF;
14
15  // #start := FALSE;
16
17  "MB_CLIENT_DB".MB_Unit_ID := 1;
18
19  "MB_CLIENT_DB"(REQ := #start,
20    DISCONNECT := NOT(#start),
21    MB_MODE := 0,
22    MB_DATA_ADDR := 40001,
23    MB_DATA_LEN := 10,
24    DONE=>#done,
25    BUSY=>#busy,
26    ERROR=>#error,
27    STATUS=>#status,
28    MB_DATA_PTR := P#DB6.DBX2.0 WORD 10,
29    CONNECT := "ModbusComm".comm_client);
30
31  #temp := "mbRead".data[1] / 10.0;
32
33  #hum := "mbRead".data[0] / 10.0;
34

```

#stonb	FALSE
#stonb	FALSE
Result	FALSE
Result	TRUE
#start	FALSE
#start	TRUE
"mbRead".liveBeat	16#82
"MB_CLIENT_DB".MB_...	16#01
#start	FALSE
#start	FALSE
#done	FALSE
#busy	FALSE
#error	FALSE
#status	16#7000
#temp	25.2
#hum	50.3

The sensor communicates slowly (9600 baud), time must be allowed for transmission. The program runs with a 2-second clock, the data is updated every 4 seconds.

It is important that the address of the sensor must also be set in the S7 program ("MB_CLIENT_DB".MB_Unit_ID := 1;)

The program uses Modbus TCP communication, where the address is irrelevant. This communication, however, is Modbus RTU (after the ethernet/RS485 converter), where the address must always be entered.

mbRead									
	Name	Data type	Offset	Start value	Monitor value	Retain	Accessible f...	Writa...	Visible in ...
1	Static					<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
2	liveBeat	Byte	0.0	16#0	16#67	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
3	data	Array[0..9] of Word	2.0			<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
4	data[0]	Word	2.0	16#0	16#01F8	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
5	data[1]	Word	4.0	16#0	16#00FD	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
6	data[2]	Word	6.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
7	data[3]	Word	8.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
8	data[4]	Word	10.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
9	data[5]	Word	12.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
10	data[6]	Word	14.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
11	data[7]	Word	16.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
12	data[8]	Word	18.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
13	data[9]	Word	20.0	16#0	16#0201	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>

The SLC code contains all FBs, FCs and DBs required for the operation. The code was developed with TIA version 16. I cannot take responsibility for its use.

This code ensures communication for this equipment only. Good luck with your application! The code contains no restrictions, restrictions, 100% free!

If you need a modified or different code, [find me here!](#)

If you just want to throw me a coffee tip, you can do it here:



If you are a manufacturer and would like an example program similar to your product, you can [find me here!](#)



The S7 program can be downloaded here, it must be exported to the TIA portal, you can find a [description of this here](#).

S7-UICPAL Modbus communication download

The program includes the following parts:

- testFB (FB): calling the program
- mbRead (DB6!): the data is read here (if the address is not DB6, the addressing must be changed in testFB at *MB_DATA_PTR*)
- ModbusComm (DB): Modbus communication settings, the address of the converter must be set here.

Important: mbRead cannot be an optimized DB due to direct addressing, you can find information [about this setting here](#).

If the status stays in the 700x range and changes continuously, then communication is working (Otherwise, you can find more information about [status codes here](#)).

[bus](#), [communication](#), [s7](#), [simatic](#), [s7 1500](#), [s7 1200](#), [scl](#), [uicpal](#), [temperature](#), [humidity](#), [modbus](#), [example](#), [download](#), [tia portal](#)

This page has been accessed for: Today: 1, Until now: 321

From:

<https://lamaplc.com/> - **lamaPLC**

Permanent link:

https://lamaplc.com/doku.php?id=sol:s7_uicpal_modbus_communication

Last update: **2026/04/21 20:47**

