

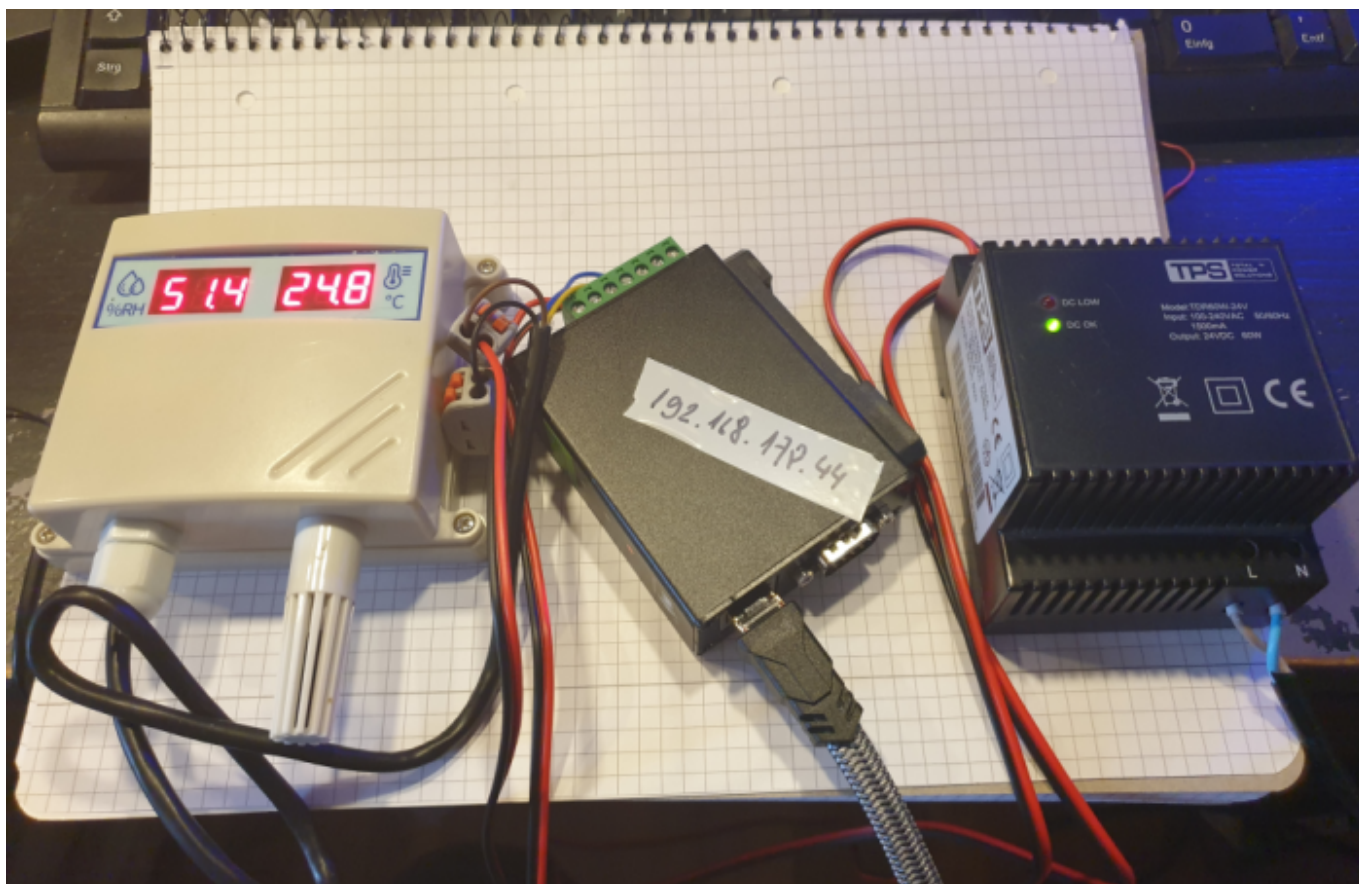
# lamaPLC: S7-1500 and UICPAL Temp.humi.sensor Modbus TCP communication

UICPAL's temperature/humidity measuring unit is a fairly cost-effective solution for controlling the air in closed spaces. The unit is also available on Aliexpress, for example, at a price well below 100 euros. The advantage is that it displays the measured values and has a [Modbus](#) communication solution. This function can be well integrated with industrial equipment, for example it can be used together with S7 PLC, the solution below describes this possibility.

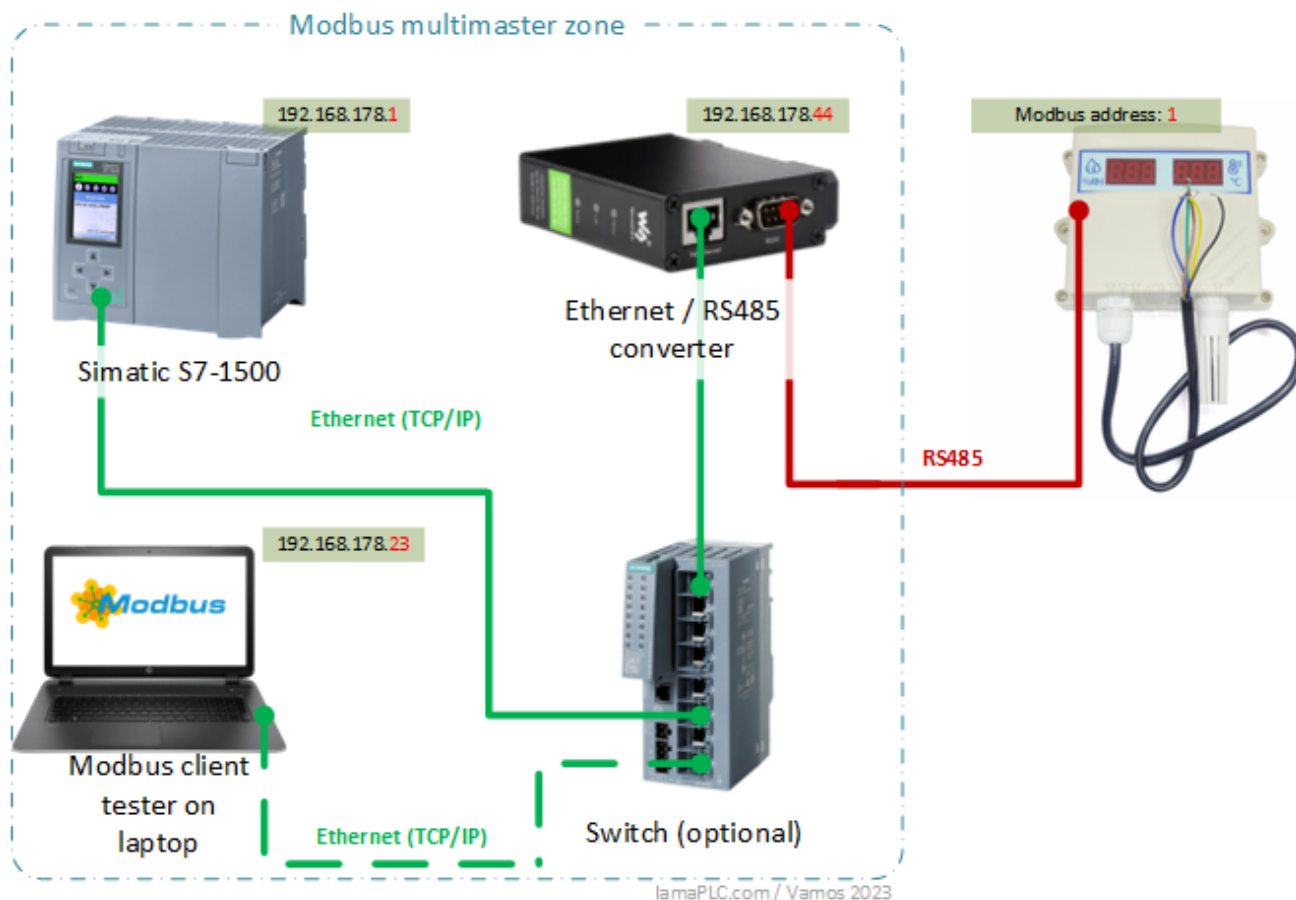


A more detailed description of the UICPAL temperature / humidity meter [can be found here](#).

Unfortunately, the unit (as far as I know) does not have a "CE" certification, which can make its application difficult in some cases.



## The UICPAL unit and the S7-1500



The UICPAL unit has RTU communication, which should be connected with an ethernet/RS485 converter as a cost-effective solution. This converter is now available directly from Simatic. It is worth starting the testing with a Modbus client tester program. If UICPAL is available from here, then there will be no major problem with Simatic.

### The steps for setting up communication:

1. Switching on UICPAL, wiring with the ethernet/RS485 converter (A TX+, B RX-). The converter is [described here](#). UICPAL is [described here](#).
2. Connecting the laptop to the ethernet/RS485 converter
3. ethernet/RS485 converter settings:
4. Setting the IP address (in the example: 192.168.178.44)
5. Setting the RS485 communication parameters: 8n1, speed: 9600 baud, addr: 1
6. Testing communication from the laptop. If the unit is not available, review the parameters and possibly replace the Modbus wires
7. If the Modbus communication works from the laptop; disconnect.
8. Uploading the PLC program, testing the PLC communication.

## The S7 programm for communication

<pre> 1  #ston(IN:=NOT(#stonb), 2    PT:=t#2s); 3 4  #stonb := #ston.Q; 5 6  IF #stonb THEN 7    IF #start THEN 8      #start := FALSE; 9    ELSE 10     #start := TRUE; 11    END_IF; 12    "mbRead".liveBeat := "mbRead".liveBeat + 1; 13  END_IF; 14 15  // #start := FALSE; 16 17  "MB_CLIENT_DB".MB_Unit_ID := 1; 18 19  "MB_CLIENT_DB"(REQ := #start, 20    DISCONNECT := NOT(#start), 21    MB_MODE := 0, 22    MB_DATA_ADDR := 40001, 23    MB_DATA_LEN := 10, 24    DONE=&gt;#done, 25    BUSY=&gt;#busy, 26    ERROR=&gt;#error, 27    STATUS=&gt;#status, 28    MB_DATA_PTR := P#DB6.DBX2.0 WORD 10, 29    CONNECT := "ModbusComm".comm_client); 30 31  #temp := "mbRead".data[1] / 10.0; 32 33  #hum := "mbRead".data[0] / 10.0; 34 </pre>	<table border="1"> <tr><td>#stonb</td><td>FALSE</td></tr> <tr><td>#stonb</td><td>FALSE</td></tr> <tr><td>Result</td><td>FALSE</td></tr> <tr><td>Result</td><td>TRUE</td></tr> <tr><td>#start</td><td>FALSE</td></tr> <tr><td>#start</td><td>TRUE</td></tr> <tr><td>"mbRead".liveBeat</td><td>16#82</td></tr> <tr><td>"MB_CLIENT_DB".MB_...</td><td>16#01</td></tr> <tr><td>#start</td><td>FALSE</td></tr> <tr><td>#start</td><td>FALSE</td></tr> <tr><td>#done</td><td>FALSE</td></tr> <tr><td>#busy</td><td>FALSE</td></tr> <tr><td>#error</td><td>FALSE</td></tr> <tr><td>#status</td><td>16#7000</td></tr> <tr><td>#temp</td><td>25.2</td></tr> <tr><td>#hum</td><td>50.3</td></tr> </table>	#stonb	FALSE	#stonb	FALSE	Result	FALSE	Result	TRUE	#start	FALSE	#start	TRUE	"mbRead".liveBeat	16#82	"MB_CLIENT_DB".MB_...	16#01	#start	FALSE	#start	FALSE	#done	FALSE	#busy	FALSE	#error	FALSE	#status	16#7000	#temp	25.2	#hum	50.3
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The sensor communicates slowly (9600 baud), time must be allowed for transmission. The program runs with a 2-second clock, the data is updated every 4 seconds.

It is important that the address of the sensor must also be set in the S7 program ("MB\_CLIENT\_DB".MB\_Unit\_ID := 1;)

The program uses [Modbus TCP](#) communication, where the address is irrelevant. This communication, however, is [Modbus RTU](#) (after the ethernet/RS485 converter), where the address must always be entered.

mbRead										
	Name	Data type	Offset	Start value	Monitor value	Retain	Accessible f...	Writa...	Visible in ...	S
1	Static					<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
2	liveBeat	Byte	0.0	16#0	16#67	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
3	data	Array[0..9] of Word	2.0			<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
4	data[0]	Word	2.0	16#0	16#01F8	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
5	data[1]	Word	4.0	16#0	16#00FD	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
6	data[2]	Word	6.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
7	data[3]	Word	8.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
8	data[4]	Word	10.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
9	data[5]	Word	12.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
10	data[6]	Word	14.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
11	data[7]	Word	16.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
12	data[8]	Word	18.0	16#0	16#0000	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
13	data[9]	Word	20.0	16#0	16#0201	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	

The SLC code contains all FBs, FCs and DBs required for the operation. The code was developed with TIA version 16. I cannot take responsibility for its use.

This code ensures communication for this equipment only. Good luck with your application! The code contains no restrictions, restrictions, 100% free!

If you need a modified or different code, [find me here!](#)

If you just want to throw me a coffee tip, you can do it here:



If you are a manufacturer and would like an example program similar to your product, you can [find me here!](#)



The S7 program can be downloaded here, it must be exported to the TIA portal, you can find a [description of this here](#).

S7-UICPAL Modbus communication download

The program includes the following parts:

- testFB (FB): calling the program
- mbRead (DB6!): the data is read here (if the address is not DB6, the addressing must be changed in testFB at *MB\_DATA\_PTR*)
- ModbusComm (DB): Modbus communication settings, the address of the converter must be set here.

Important: mbRead cannot be an optimized DB due to direct addressing, you can find information [about this setting here](#).

If the status stays in the 700x range and changes continuously, then communication is working (Otherwise, you can find more information about [status codes here](#)).

[bus, communication, s7, simatic, s7 1500, s7 1200, scl, uicpal, temperature, humidity, modbus, example, download, tia portal](#)

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